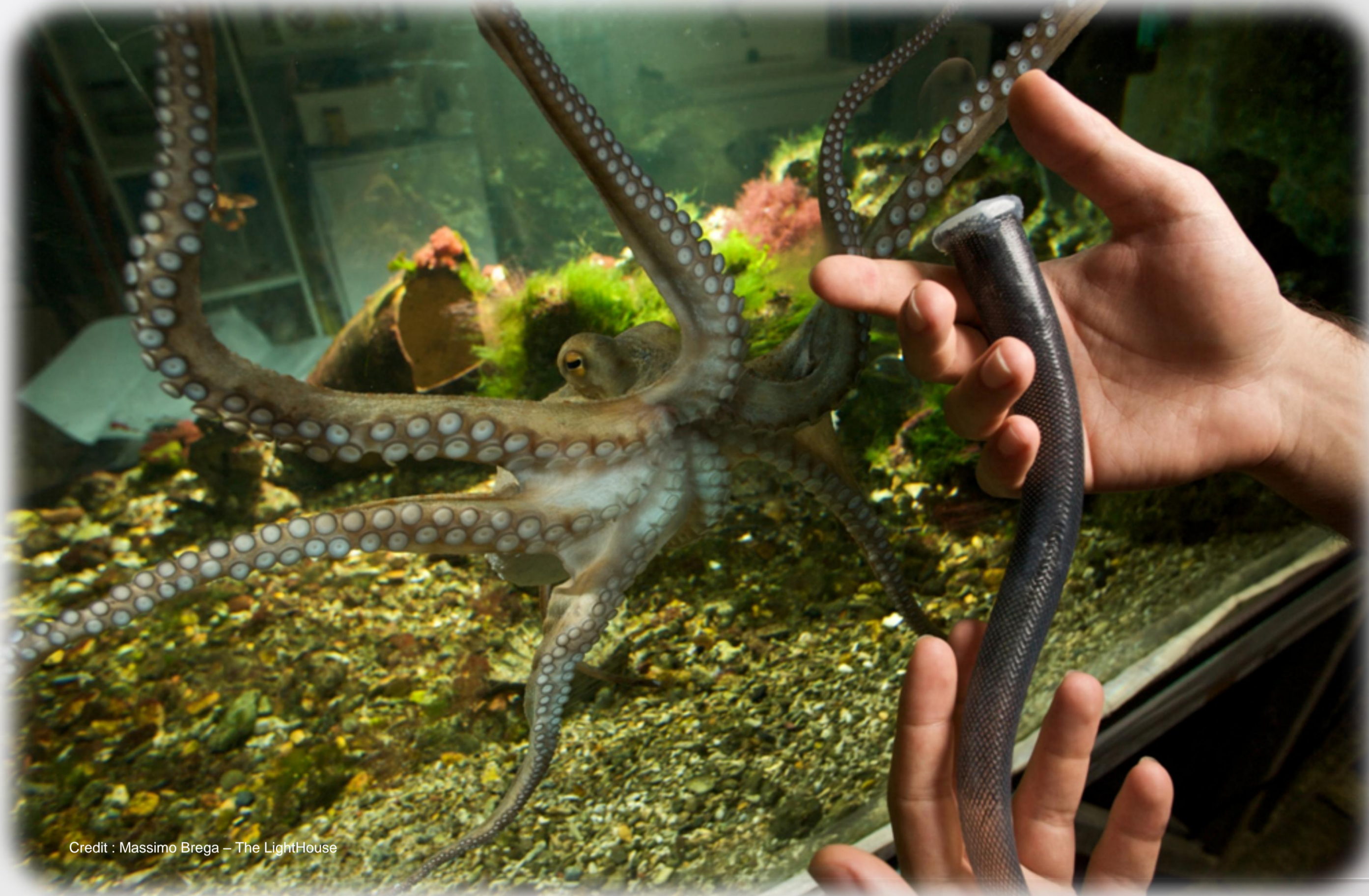




OCTOPUS



Novel Design Principles and Technologies for a New Generation of High Dexterity Soft-bodied Robots Inspired by the Morphology and Behaviour of the Octopus

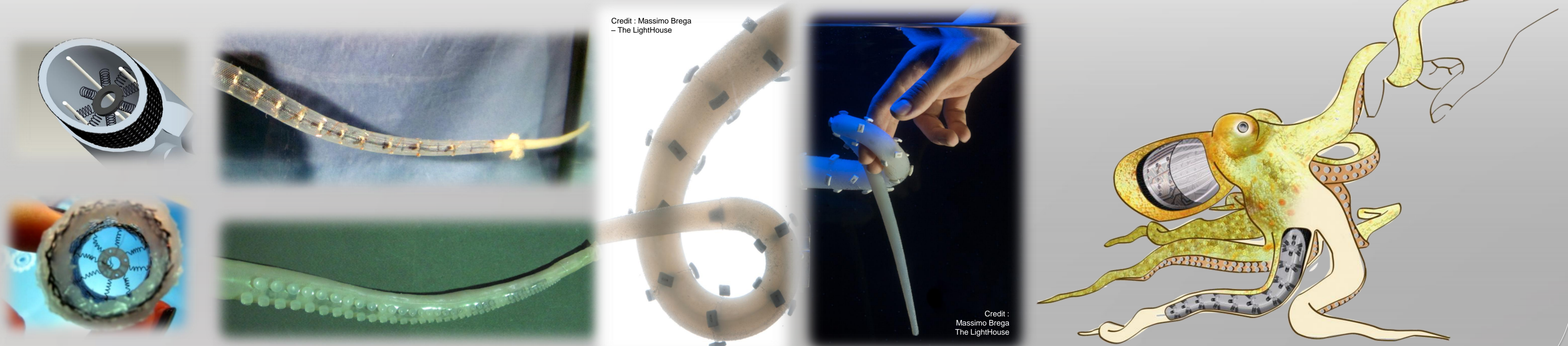


The octopus as a paradigm for Embodied Intelligence and as source of inspiration for Soft Robotics

- The octopus has no rigid structures and it can squeeze into small apertures
- The octopus peculiar muscular structure (*muscular hydrostat*) provides it with high strength (up to 40N) in grasping
- The octopus shows rich behaviour, learning capability, memory



The OCTOPUS project aims at understanding the key principles of the octopus body and brain by building a soft 8-arm robot, able to move in water, to elongate its arms, to reach and grasp, and to locomote.



The OCTOPUS Integrating Project



SSSA (I)
- Coordinator -
Scuola Superiore Sant'Anna
Cecilia Laschi



HUJI (IL)
Hebrew University
of Jerusalem
Binyamin Hochner



Weizmann (IL)
Weizmann Institute
of Science
Tamar Flash



UZH (CH)
University of
Zurich
Rolf Pfeifer



IIT (I)
Italian Institute of Technology
Fabio Benfenati
Darwin Caldwell



UREAD (UK)
University of
Reading
Richard Bonser



FORTH (GR)
Foundation for Research and
Technology - Hellas
Dimitris P. Tsakiris

Project Coordinator: Prof. Cecilia Laschi (cecilia.laschi@sssup.it)